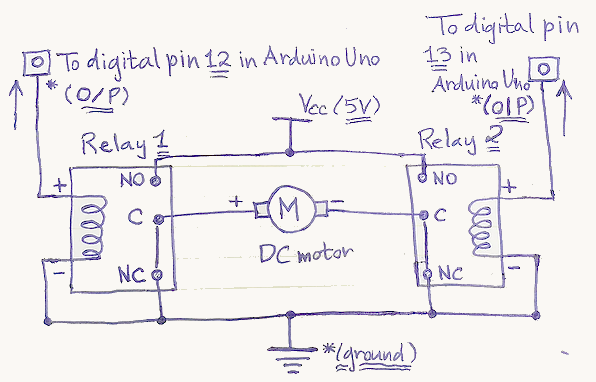
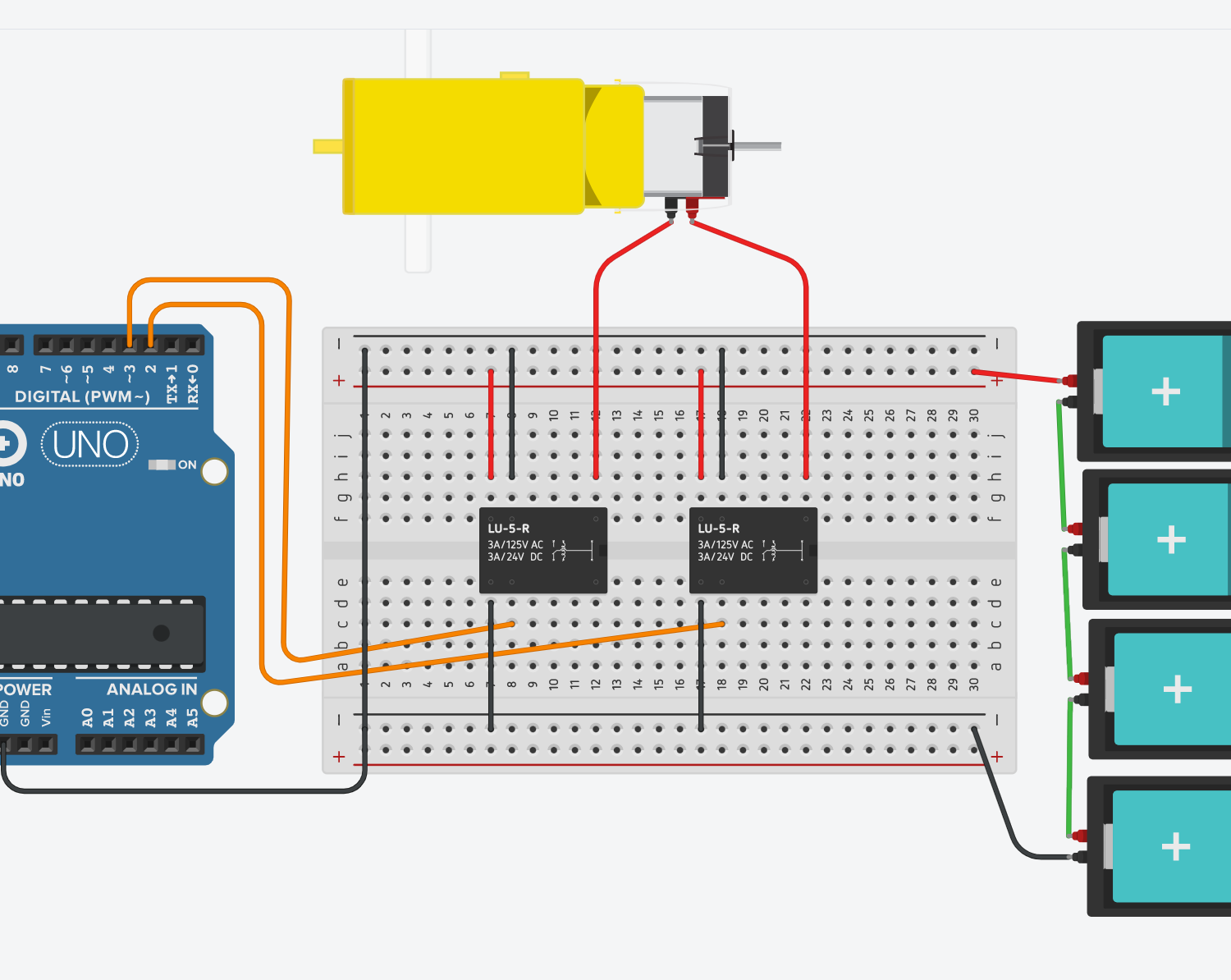
**PONTE AD H CON 2 RELE’**

Controllo verso di rotazione motori in tensione continua.



Schema Thinkercad



**Codice Arduino**

int incomingByte = 0; // for incoming serial data

void setup() {

pinMode(2, OUTPUT);

pinMode(3, OUTPUT);

Serial.begin(9600);

}

void loop() {

if (Serial.available() > 0) {

// leggo numeri da 0-9 (1 cifra) associati

incomingByte = Serial.parseInt();

Serial.println(incomingByte);

if (incomingByte==1) {

Serial.println("M1 ORARIO");

digitalWrite(2, HIGH);

digitalWrite(3, LOW);

}

else if (incomingByte==2) {

Serial.println("M1 ANTIORARIO");

digitalWrite(2, LOW);

digitalWrite(3, HIGH);

}

else if (incomingByte==3) {

Serial.println("STOP");

digitalWrite(2, HIGH);

digitalWrite(3, HIGH);

}

else if (incomingByte==4) {

Serial.println("STOP");

digitalWrite(2, LOW);

digitalWrite(3, LOW);

}

else

{

Serial.println("????");

}

}

}